ACADEMY OF SPINAL CORD INJURY PROFESSIONALS



Leg Stretching by a Fully Wearable, Hybrid/FES Exoskeleton in Spinal Cord Injury Patients with Spasticity

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Objective:

- Spasticity is a debilitating condition in people with chronic spinal cord injury (SCI)
- The objective is to develop a *wearable device* that applies safe, customized forces to assist with *leg stretching*, as an alternative to manual stretching



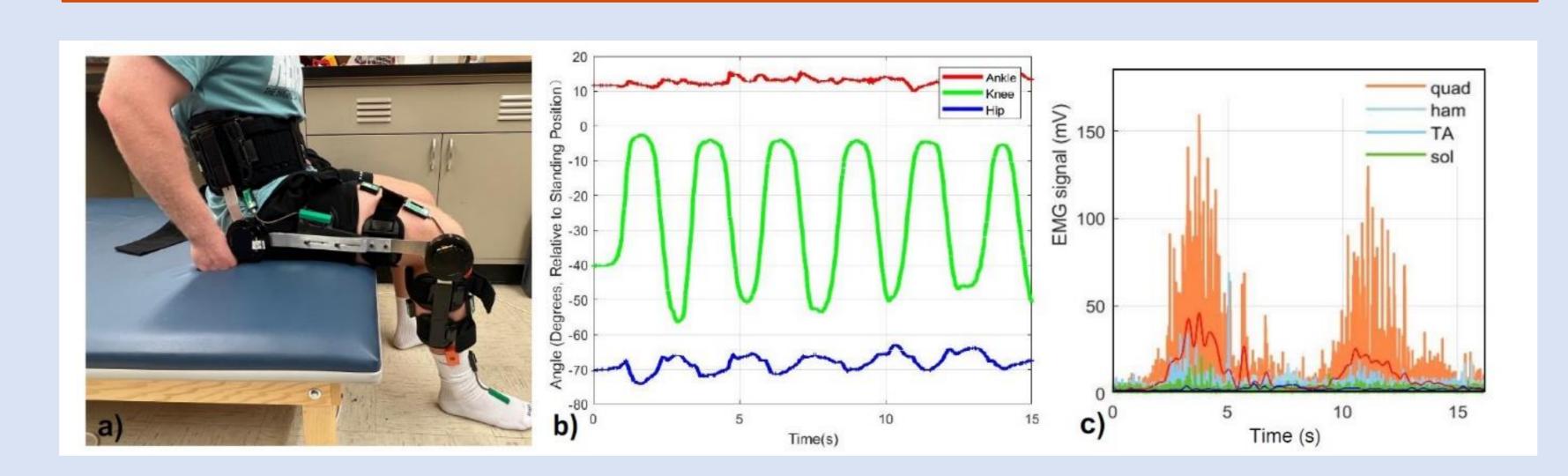


Design/Methods:

- •1 able-bodied individual
- •Rotation of the hip, knee, and ankle joints bilaterally at low to moderate stretching rates (e.g., 10-50 cycles/minute)
- •The movements are attempted 3-4 times and rest breaks are provided in between repetitions

Results:

- •Stretching movements: ankle plantar flexion and dorsiflexion, knee extension, hip flexion with the knee flexed, and toe flexion and extension
- •Joint kinematics, leg postures, applied forces, and surface muscle activity → preliminary performance of the device
- •Safe range of motion for each participant



Learning Objective:

To establish the feasibility of a wearable robotic exoskeleton to provide leg stretching in people with spasticity

Conclusion:

- •Fully customizable and safer ondemand stretching approach
- •Data analysis and post-processing to inform the next phase of testing

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